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Some Problems on Holomorphic Sectional Curvature

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ABSTRACT: Purpose of the present paper is to study of Holomorphic Sectional Curvature. In section 2, we have defined and studied H-Projective Curvature tensor. Section 3 is devoted for Recurrent Sasakian manifolds and Ricci Recurrent Sasakian manifold.

I. INTRODUCTION

An n-dimensional Sasakian space M^n is an odd dimensional Riemannian space, which admits a Unit Killing vector field η^{λ} satisfying:

(1.1)
$$\eta_{k,i,j} = \eta_j g_{ik} - \eta_k g_{ij}$$

Wherein a comma (,) followed by index denotes the operation of covariant differentiation with regard to the fundamental tensor g_{ij} of the Riemannian space.

(1.2) $R^{h}_{ijk} = \partial_{i} \left\{ \begin{smallmatrix} h \\ j & k \end{smallmatrix} \right\} - \partial_{j} \left\{ \begin{smallmatrix} h \\ i & j \end{smallmatrix} \right\} + \left\{ \begin{smallmatrix} h \\ i & j \end{smallmatrix} \right\} \left\{ \begin{smallmatrix} j \\ j & k \end{smallmatrix} \right\} - \left\{ \begin{smallmatrix} h \\ j & k \end{smallmatrix} \right\} \left\{ \begin{smallmatrix} l \\ i & k \end{smallmatrix} \right\}$ Whereas the Ricci tensor and the scalar curvature are respectively given by

(1.3)
$$R_{jk} = R^i_{\ ijk},$$

$$(1.4) R = R_{jk} g^{-1}$$

and

(1.5)
$$\partial_i = \left(\frac{\partial}{\partial x^i}\right)$$

A tensor S_{ii} is defined as

(1.6)
$$S_{ij} = -F^a_{\ i} R_{aj}$$

then we have
(1.7) $S_{ij} = -S_{ji}$
and

(1.8)
$$F^{a}_{\ i} S_{aj} = -S_{ia} F^{a}_{\ j}$$

II. H-PROJECTIVE CURVATURE TENSOR

H-Projective Curvature tensor in the Sasakian space is defined as [5]:

(2.1)
$$P^{h}_{ijk} = R^{h}_{ijk} + \left\{ \frac{1}{(n+2)} \right\} \left(R_{ij} \,\delta^{h}_{j} - R_{jk} \,\delta^{h}_{i} + S_{ik} \,F^{h}_{j} - S_{ik} F^{h}_{j} - S_{jk} F^{h}_{i} + 2S_{ij} \,F^{h}_{k} \right)$$

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Definition 2.1

A Sasakian manifold is called H-Projective Recurrent if it satisfies the following condition.

$$(2.2) \nabla_l P^{n}_{\ ijk} = \lambda_l P^{n}_{\ ijk}$$

Wherein λ_1 is H-Projective Recurrent vector.

Definition 2.2

A Sasakian manifold is said to be H-Projective Symmetric if it satisfied the following condition. (2 3) $\nabla P^h = 0$

$$(2.3) \mathbf{v}_l \mathbf{P}_{ijk} = \mathbf{0}$$

Definition 2.3

A Sasakian manifold is termed as H-Projectively flat if

(2.4)
$$P^n_{ijk} = 0.$$

H-Conformal (or Bockner) Curvature tensor in the Sasakian space is given by

$$(2.5) B^{h}_{ijk} = R^{h}_{ijk} + \{1/(n+4) \{ (R_{ik} \delta^{h}_{j} - R_{jk} \delta^{h}_{i} + g_{ik} R^{h}_{j} - g_{jk} R^{h}_{i} + S_{ik} F^{h}_{j} - S_{jk} F^{h}_{i} + F_{ik} S^{h}_{j} - F_{jk} F^{h}_{i} + 2S_{ij} F^{h}_{k} + 2F_{ij} S^{h}_{k} \} - \{ R/(n+2)(n+4) \} (g_{ik} \delta^{h}_{j} - g_{jk} \delta^{h}_{i} + F_{ik} F^{h}_{j} - F_{jk} F^{h}_{i} + 2F_{ij} F^{h}_{k} \}$$

Definition 2.4

A Sasakian space satisfying the relation

 $(2.6) \nabla_a B^h_{ijk} - \lambda_a B^h_{ijk} = 0$

is termed as Sasakian space with Recurrent H-Conformal Curvature tensor.

H- Conharmonic Curvature tensor is given by

(2.7)
$$T^{h}_{ijk} = R^{h}_{ijk} + \{1/(n+4)\} (R_{ik}\delta^{h}_{j} - R_{ik}\delta^{h}_{i} + g_{ik}R^{h}_{j} - g_{jk}R^{h}_{i} + S_{ik}F^{h}_{j} - S_{jk}F^{h}_{i} + F_{ik}S^{h}_{j} - F_{jk}S^{h}_{i} + 2S_{ij}F^{h}_{k} + 2F_{ij}S^{h}_{k} \}.$$

Definition 2.5

A Sasakian space satisfying the following condition

$$(2.8) \nabla_a T^h_{\ ijk} - \lambda_a T^h_{\ ijk} = 0$$

for some non-zero Recurrence vector λ_a will be called a Sasakian space with Recurrent H-Conharmonic Curvature tensor or Recurrent Bochner Curvature tensor.

H-Concircular tensor is given by

(2.9)
$$C^{h}_{ijk} = R^{h}_{ijk} + \{R/n(n+2)\}(g_{ik}\delta^{h}_{j} - g_{jk}\delta^{h}_{i} + F_{ik}F^{h}_{j})$$

Definition 2.6

A Sasakian space is called Sasakian space with Recurrent H- Concircular Curvature tensor, if it satisfies.

$$(2.10) \nabla_a C^h_{ijk} - \lambda_a C^h_{ijk} = 0$$

for some non-zero Recurrence vector λ_a .

III. RICCI RECURRENT SASAKIAN MANIFOLDS

A Sasakian space is said to be recurrent if, we have

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$$(3.1) \nabla_a R^h_{ijk} - \lambda_a R^h_{ijk} = 0$$

for some non-zero recurrence vector λ_a .

Definition 3.2

A Sasakian space is termed as Ricci Recurrent if it satisfies the relation

 $(3.2) \nabla_a R_{ij} - \lambda_a R_{ij} = 0,$

Remark 3.1

It is noteworthy that a Ricci Recurrent Sasakian space is also known as Semi Recurrent Sasakian space.

Multiplying equation (3.2) by g^{ij} , we obtain

(3.3) $\nabla_a R - \lambda_a R = 0$

Remark 3.2

From (3.1), if follows that every Sasakian Recurrent space is Sasakian Ricci-Recurrent, but the converse is not necessarily true.

IV. HOLOMORPHIC SECTIONAL CURVATURE

The Holomorphic Sectional Curvature of a Sasakian space with regard to a vector v^h is given by

(4.1)
$$K_{mjlh}F^{m}_{\ k}v^{k}v^{j}F^{l}_{\ i}v^{i}v^{h} + K(g_{kj}v^{k}v^{j}g_{ih}v^{i}v^{h}) = 0.$$

Remark 4.1

If the Holomorphic Sectional Curvature is constant with regard to any vector at all points then the space is said to be a space of Constant Holomorphic Sectional Curvature.

Definition 4.1

A vector v^h in the Sasakian manifold is called H-Projective vector if it satisfies the relation

(4.2) $L_v P^h_{ijk} = 0.$

Transvecting equation (4.2) by g_{hm} , we get

(4.3) $L_v P_{iikm} = 0$

Wherein L_{ν} , denotes the operator of Lie derivative.

In a Sasakian space of Constant Holomorphic Sectional Curvature, the Curvature tensor is given by

(4.4)
$$K_{kjih} = (K/4) \{ (g_{hk} g_{ij} - g_{jh} g_{ik}) + (F_{hk} F_{jh} - F_{jh} F_{ik} - 2F_{jk} F_{ih}) \}$$

Therefore, if the Sasakian space is of Constant Holomorphic Sectional Curvature, then

$$(4.5) \nabla_l P_{ijkh} = 0$$

Transvecting equation (4.5) with g^{kh} yields

(4.6) $\nabla_l P_{ii} = 0$

In this regard, we have the following heorem:

Theorem 4.1

A Sasakian space of Constant Holomorphic Sectional Curvature is H-Projective Symmetric.

Contracting equation (4.4) by g^{ih} , we obtain

(4.7)
$$K_{jk} = (K/2) (F^m_{j} F_{mk} - F^m_{k} F_{mi} + 2F F_{jk})$$

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Transvecting equation (2.1) by g_{hm} , we get

(4.8)
$$P_{ijkm} = R_{ijkm} + \left\{ \frac{1}{(n+2)} \right\} \left(g_{jm} R_{ik} - g_{im} R_{jk} + S_{ik} F_{jm} - S_{jk} F_{im} + 2S_{ij} F_{km} \right)$$

Differentiating equation (4.8) convariantly, we obtain

(4.9)
$$\nabla_{l} P_{ijkm} = \nabla_{l} R_{ijkm} + \{1/(n+2)\} \{g_{jm} (\nabla_{l} R_{ik}) - g_{im} (\nabla_{l} R_{jk}) + \nabla_{l} (S_{ik} F_{jm}) - \nabla_{l} (S_{jk} F_{im}) + 2\nabla_{l} (S_{ij} F_{km})\}$$

Case I

If a Sasakian manifold is H-Projectively Flat then equation (2.1) becomes reduced in the form

(4.10)
$$R^{h}_{ijk} = -\{1/(n+2)\}(R_{ik}\,\delta^{h} - R_{jk}\,\delta^{h}_{i} + S_{ik}\,F^{h}_{j} - S_{jk}F^{h}_{i} + 2S_{ij}\,F^{h}_{k})$$

Transvecting equation (4.10) by g_{hm} , we obtain

(4.11)
$$R_{ijkm} = -\{1/(n+2)\} (R_{ik}\delta^{h}_{\ j} - R_{jk}\delta^{h}_{\ i} + S_{ik}F^{h}_{\ j} - S_{jk}F^{h}_{\ i} + 2S_{ij}F^{h}_{\ k})$$

Transvecting equation (4.8) with g^{km} and using equation (1.8), we get

(4.12)
$$P_{ij} = R_{ij} + \{2/(n+2)\} (S_{in} F^n_j + FS_{ij})$$

Differentiating equation (4.12) covariantely, we obtain

(4.13)
$$\nabla_l P_{ij} = \nabla_l R_{ij} + \{2/(n+2)\}\{\nabla_l (S_{in}F_j^n) + \nabla_l (FS_{ij})\}$$

Case II

If the Sasakian space is of Constant Holomorphic Sectional Curvature, then equation (4.13) becomes reduced in the form

(4.14)
$$\nabla_l R_{ij} = -\{2/(n+2)\}\{\nabla_l (S_{ik} F^k_{j}) + \nabla_l (FS_{ij})\}.$$

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