



Common Fixed Point Theorem in Probabilistic 2-Metric Space by Weak Compatibility

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ABSTRACT: The object of this paper is to extend and generalize the result of Vasuki [8] from fuzzy metric space to probabilistic 2-metric space using the concept of weak compatibility.

Keywords: Common fixed point, Menger space, Probabilistic 2-metric space, compatible maps, semi-compatible maps, weak compatible maps.

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I. INTRODUCTION

There have been a number of generalizations of metric space. One such generalization is Menger space initiated by Menger [3]. It is a probabilistic generalization in which we assign to any two points x and y , a distribution function $F_{x,y}$. Schweizer and Sklar [5] studied this concept and gave some fundamental results on this space.

The notion of compatible mapping in a Menger space has been introduced by Mishra [4]. Sessa [7] initiated the tradition of improving commutativity in fixed point theorems by introducing the notion of weakly commuting maps in metric space. Jungck [1] soon enlarged this concept by introducing the concept of compatible maps. Recently, Jungck and Rhoades [2] termed a pair of self maps to be coincidentally commuting or equivalently weak-compatible if they commute at their coincidence points. The concept of R-weakly commuting maps in fuzzy metric space has been introduced by Vasuki [8].

The main object of this paper is to extend and generalize the result of Vasuki [8] from fuzzy metric space to probabilistic 2-metric space in the following ways :

- (i) To increase the number of maps from 2 to 4.
- (ii) To relax the continuity requirement of the maps completely.

II. PRELIMINARIES

Definition 2.1. [4] A mapping $F : R \rightarrow R^+$ is called a *distribution* if it is non-decreasing left continuous with $\inf \{ F(t) \mid t \in R \} = 0$ and $\sup \{ F(t) \mid t \in R \} = 1$.

We shall denote by L the set of all distribution functions while H will always denote the specific distribution function defined by

$$H(t) = \begin{cases} 0 & , t \leq 0 \\ 1 & , t > 0 \end{cases}$$

Definition 2.2. [9] A *probabilistic 2-metric space (2-PM space)* is an ordered pair (X, F) where X is an abstract set and F is a function defined on $X \times X \times X$ into L , the collection of all distribution functions. The value of F at $(x, y, z) \in X \times X \times X$ is generally represented by $F_{x,y,z}$ or $F(x, y, z)$. The distribution function $F(x, y, z)$ satisfy the following conditions:

- (1) $F(x, y, z; 0) = 0$,
- (2) For all distinct x, y in X there exists a point z in X such that $F(x, y, w; t) < 1$ for some $t > 0$.
- (3) $F(x, y, z; t) = 1$ for all $t > 0$ if and only if at least two of the three points are equal.
- (4) $F(x, y, z; t) = F(x, z, y; t) = F(y, z, x; t)$ (Symmetry)
- (5) If $F(x, y, z; t_1) = F(x, z, y; t_2) = F(y, z, x; t_3) = 1$ then $F(x, y, z; t_1 + t_2 + t_3) = 1$.

Definition 2.3. [9] The mapping $t : [0, 1] \times [0, 1] \times [0, 1] \rightarrow [0, 1]$ is a *t-norm* if t satisfies the following conditions:

- (1) $t(x, 1, 1) = x, t(0, 0, 0) = 0$;
- (2) $t(x, y, z) = t(x, z, y) = T(z, y, x)$;
- (3) $t(x_1, y_1, z_1) \geq t(x_2, y_2, z_2)$ for $x_1 \geq x_2, y_1 \geq y_2, z_1 \geq z_2$;
- (4) $t(t(x, y, z), p, q) = t(x, t(y, z, p), q) = t(x, y, t(z, p, q))$.

Definition 2.4. [9] A Menger probabilistic 2-metric space is a triplet (X, F, t) where (X, F) is a 2-PM space and t is a t -norm satisfying the following triangle inequality :

$$F(x, y, z; t_1 + t_2 + t_3) \geq y(F(x, y, p; t_1), F(x, p, z; t_2), F(p, y, z; t_3)) \text{ for all } x, y, z, p \in X \text{ and } t_1, t_2, t_3 \geq 0.$$

Definition 2.5. [9] A sequence $\{x_n\}$ in a 2-Menger space (X, F, t) is said to converge to a point $x \in X$ if for each $\epsilon > 0$ and $\lambda > 0$ there exists a positive integer $M(\epsilon, \lambda)$ such that

$$F(x_n, x, a; \epsilon) > 1 - \lambda, \text{ for all } a \in X \text{ and } n \geq M(\epsilon, \lambda).$$

The sequence $\{x_n\}$ converges to x if and only if

$$F(x_n, x, a; t) = H(t) \text{ for all } a,$$

where H is the distribution function defined as above.

Definition 2.6. [9] A sequence $\{x_n\}$ in a 2-Menger space (X, F, t) is said to be Cauchy if, for each $\epsilon > 0$ and $\lambda > 0$ there exists a positive integer $M(\epsilon, \lambda)$ such that

$$F(x_n, x_m, a; \epsilon) > 1 - \lambda, \text{ for all } a \in X \text{ and } n, m \geq M(\epsilon, \lambda).$$

Lemma 2.1. [9] Let $\{x_n\}$ be a sequence in a 2-Menger space (X, F, t) where t is continuous and satisfies $t(x, x, x) \geq x$ for all $x \in (0, 1)$. If there exists a positive number $h < 1$ such that

$$F(x_{n+1}, x_n, a; hu) \geq F(x_n, x_{n-1}, a; u), \quad n = 1, 2, 3, \dots$$

for all $a \in X$ and $u \geq 0$ then $\{x_n\}$ is a Cauchy sequence in X .

Definition 2.7. Self mappings A and S of a Menger probabilistic 2-metric space (X, F, t) are said to be compatible if $F_{ASx_n, SAx_n, a}(x) \rightarrow 1$ for all $a \in X, x > 0$, whenever $\{x_n\}$ is a sequence in X such that $Ax_n, Sx_n \rightarrow u$ for some u in X , as $n \rightarrow \infty$.

Definition 2.7. Self maps S and T of a Menger probabilistic 2-metric space (X, F, t) are said to be weak-compatible if they commute at their coincidence points, i.e. $Sx = Tx$ for $x \in X$ implies $STx = TSx$.

Remark 2.1. It is obvious that the concept of weak compatibility is more general than that of compatibility.

Lemma 2.1. [9] Let $\{p_n\}$ be a sequence in a Menger probabilistic 2-metric space (X, F, t) with continuous t -norm and $t(x, x) \geq x$. Suppose, for all $x \in [0, 1]$, there exists $k \in (0, 1)$ such that for all $x > 0$ and $n \in \mathbb{N}$,

$$F_{p_n, p_{n+1}, a}(kx) \geq F_{p_{n-1}, p_n, a}(x)$$

Or
$$F_{p_n, p_{n+1}, a}(x) \geq F_{p_{n-1}, p_n, a}(k^{-1}x).$$

Then $\{p_n\}$ is a Cauchy sequence in X .

In [8], Vasuki proved the following result:

Theorem 2.1. Let $(X, M, *)$ be a complete fuzzy metric space and f and g be R -weakly commuting self mappings of X satisfying the condition

$$M(fx, fy, t) \geq r[M(gx, gy, t)],$$

where $r : [0, 1] \rightarrow [0, 1]$ is a continuous function such that $r(t) > t$ for each $0 < t < 1$. If $f(x) \subset g(x)$ and either f or g is continuous then f and g have a unique common fixed point.

III. MAIN RESULT

Theorem 3.1. Let A, B, S and T be self mappings of a complete probabilistic 2-metric space (X, F, \min) satisfying

- (3.1) $A(X) \subset T(X), B(X) \subset S(X)$;
- (3.2) One of $A(X), B(X), T(X)$ or $S(X)$ is complete;
- (3.3) Pairs (A, S) and (B, T) are weak compatible;
- (3.4) for all $x, y \in X$ and $t > 0$,

$$F_{Ax, By, a}(t) \geq rF_{Sx, Ty, a}(t)$$

where $r : [0, 1] \rightarrow [0, 1]$ is some continuous function such that $r(t) > t$, for each $0 < t < 1$.

Then A, B, S and T have a unique common fixed point in X .

Proof. Let $x_0 \in X$ be any arbitrary point.

As $A(X) \subset T(X)$ and $B(X) \subset S(X)$, there exists $x_1, x_2 \in X$ such that

$$Ax_0 = Tx_1 \text{ and } Bx_1 = Sx_2.$$

Inductively, construct sequences $\{y_n\}$ and $\{x_n\}$ in X such that

$$y_{2n+1} = Ax_{2n} = Tx_{2n+1}, \quad y_{2n+2} = Bx_{2n+1} = Sx_{2n+2} \text{ for } n = 0, 1, 2, \dots$$

Now, using (3.4) with $x = x_{2n}$ and $y = x_{2n+1}$, we obtain that

$$\begin{aligned} F_{y_{2n+1}, y_{2n+2}, a}(t) &= F_{Ax_{2n}, Bx_{2n+1}, a}(t) \\ &\geq rF_{Sx_{2n}, Tx_{2n+1}, a}(t) \\ &= rF_{y_{2n}, y_{2n+1}, a}(t) \\ &> F_{y_{2n}, y_{2n+1}, a}(t) \text{ for } t \in (0, 1). \end{aligned}$$

Similarly,

$$F_{y_{2n+2}, y_{2n+3}, a}(t) > F_{y_{2n+1}, y_{2n+2}, a}(t).$$

In general,

$$F_{y_{n+1}, y_n, a}(t) > F_{y_n, y_{n-1}, a}(t).$$

Thus, $\{F_{y_{n+1}, y_n, a}(t), n > 0\}$ is an increasing sequence of positive real numbers in $[0, 1]$ and therefore tends to a limit $L \leq 1$.

If $L < 1$, then $F_{y_{n+1}, y_n, a}(t) = L > r(1) > 1$,

which is a contradiction.

Hence, $L = 1$.

Hence, for all n and p,

$$F_{y_n, y_{n+p}, a}(t) = 1.$$

Thus, $\{y_n\}$ is a Cauchy sequence in X. By completeness of X, $\{y_n\}$ converges to $z \in X$.

Hence, its subsequences

$$\{Ax_{2n}\} \rightarrow z, \{Sx_{2n}\} \rightarrow z, \{Tx_{2n+1}\} \rightarrow z \text{ and } \{Bx_{2n+1}\} \rightarrow z. \quad \dots(3.1)$$

Case I. T(X) is complete.

In this case $z \in T(X)$.

Hence, there exists $u \in X$ such that $z = Tu$. $\dots(3.2)$

Step I. By putting $x = x_{2n}$ and $y = u$ in (3.4), we obtain

$$F_{Ax_{2n}, Bu, a}(t) \geq rF_{Sx_{2n}, Tu, a}(t). \quad \dots(3.3)$$

Taking limit as $n \rightarrow \infty$ and using (1), we get

$$F_{z, Bu, a}(t) \geq rF_{z, Tu, a}(t) = rF_{z, z, a}(t) = r(1) = 1 \quad \dots(3.4)$$

which gives $z = Bu = Tu$.

As (B, T) is weak compatible, we get

$$TBu = BTu,$$

i.e. $Tz = Bz$. $\dots(3.5)$

Step II. By putting $x = x_{2n}$ and $y = z$ in (3.4), we obtain that

$$F_{Ax_{2n}, Bz, a}(t) \geq rF_{Sx_{2n}, Tz, a}(t).$$

Taking limit as $n \rightarrow \infty$ and using (1), (2) and (3.5), we get

$$F_{z, Bz, a}(t) \geq rF_{z, z, a}(t) = r(1) = 1,$$

which gives $z = Bz$ and we get

$$Tz = Bz = z. \quad \dots(3.6)$$

Step III. As $B(X) \subset S(X)$, there exists $v \in X$ such that $z = Bz = Sv$.

By putting $x = v$, $y = z$ in (3.4), we get

$$F_{Av, Bz, a}(t) \geq rF_{Sv, Tz, a}(t)$$

i.e. $F_{Av, z, a}(t) \geq rF_{z, z, a}(t) = 1$

which gives $Av = z = Sv$ and weak compatibility of (A, S) gives

$$ASv = SAV,$$

i.e. $Az = Sz$.

Step IV. By putting $x = z$, $y = z$ in (3.4) and assuming $Az \neq Bz$, we get

$$F_{Az, Bz, a}(t) \geq rF_{Sz, Tz, a}(t) = rF_{Az, Bz, a}(t) > F_{Az, Bz, a}(t),$$

which is a contradiction and we get $Az = Bz$.

Combining all the results, we get

$$z = Az = Bz = Sz = Tz,$$

i.e., z is a common fixed point of the four self maps A, B, S and T.

Case II. S(X) is complete.

In this case $z \in S(X)$. Hence there exists $w \in X$ such that $z = Sw$.

Step I. By putting $x = w$, $y = x_{2n+1}$ in (3.4), we get

$$F_{Aw, Bx_{2n+1}, a}(t) \geq rF_{Sw, Tx_{2n+1}, a}(t).$$

Taking limit as $n \rightarrow \infty$ and using (3) and (4), we obtain that

$$F_{Aw, z, a}(t) \geq rF_{z, z, a}(t) = r(1) = 1.$$

Hence, $z = Aw = Sw$ and weak comatibility of (A, S) gives

$$ASw = SAw,$$

i.e. $Az = Sz$. $\dots(3.7)$

Step II. Put $x = z$, $y = x_{2n+1}$ in (3.4) and we get

$$F_{Az, Bx_{2n+1}, a}(t) \geq rF_{Sz, Tx_{2n+1}, a}(t).$$

Taking limit as $n \rightarrow \infty$ and using (3) and (4), we obtain that

$$F_{Az, z, a}(t) \geq rF_{Az, z, a}(t) > F_{Az, z, a}(t), \text{ if } F_{Az, z, a}(t) > 0,$$

which is a contradiction, hence $z = Az = Sz$.

Step III. As $A(X) \subset T(X)$, there exists some $u_1 \in X$, such that

$$z = Az = Tu_1.$$

By putting $x = x_{2n}$, $y = u_1$ in (3.4), we have

$$F_{Ax_{2n}, Bu_1, a}(t) \geq rF_{Sx_{2n}, Tu_1, a}(t).$$

Taking limit as $n \rightarrow \infty$ and using (1) and (2), we get

$$F_{z, Bu_1, a}(t) \geq rF_{z, z, a}(t) = r(1) = 1.$$

Thus $z = Bu_1 = Tu_1$.

As (B, T) is weakly compatible, we get

$$TBu = BTu,$$

i.e. $Tz = Bz$.

Step IV. By putting $x = z$, $y = z$ in (3.4) and assuming $Az \neq Bz$, we have

$$F_{Az, Bz, a}(t) \geq rF_{Sz, Tz, a}(t) = rF_{Az, Bz, a}(t) > F_{Az, Bz, a}(t),$$

which is a contradiction and we suppose $Az = Bz = z$.

Combining all the results, we get

$$z = Az = Bz = Sz = Tz,$$

i.e. z is a common fixed point of the maps A, B, S and T in this case also.

Case III. As A(X) or B(X) is complete.

As $A(X) \subset T(X)$ and $B(X) \subset S(X)$, the result follows from case I and case II respectively.

Uniqueness. Let z and z' be the two common fixed points of the maps A, B, S and T then $z = Az = Bz = Sz = Tz$ and $z' = Az' = Bz' = Sz' = Tz'$.

On assuming $z \neq z'$ and using (3.4), we get

$$\begin{aligned} F_{z, z'}(t) &= F_{Az, Bz', a}(t) \\ &\geq rF_{Sz, Tz', a}(t) \\ &= rF_{z, z', a}(t) \\ &> F_{z, z', a}(t), \text{ if } F_{z, z', a}(t) > 0 \end{aligned}$$

which is a contradiction hence $z = z'$ and we get z is the unique common fixed point of the four self maps.

If we take $A = B = f$ and $S = T = g$ in theorem 3.1., we get

Corollary 3.2. Let (X, F, \min) be a complete probabilistic 2-metric space and f and g are weak compatible self mappings of X satisfying the conditions :

$$F_{fx, fy, a}(t) \geq rF_{gx, gy, a}(t)$$

where, $r : [0, 1] \rightarrow [0, 1]$ is a continuous function such that $r(t) > t$ for each $0 < t < 1$.

If $f(x) \subset g(x)$ and either $f(x)$ or $g(x)$ is complete then f and g have a unique common fixed point in X .

Now, on taking $S = I$, the identity map on X , in theorem 3.1, we have the following result for three self maps none of which is continuous and just a pair of them is needed to be weak compatible only.

Corollary 3.3. Let A, B and T be self mappings of a complete probabilistic 2-metric space (X, F, \min) satisfying :

$$A(X) \subset T(X); \quad \dots(3.8)$$

$$(B, T) \text{ is weak compatible}; \quad \dots(3.9)$$

$$\forall x, y \in X \text{ and } t > 0, \quad \dots(3.10)$$

$$F_{Ax, By, a}(t) \geq rF_{x, Ty, a}(t),$$

where $r : [0, 1] \rightarrow [0, 1]$ is some continuous function such that $r(t) > t$ for each $0 < t < 1$.

Then A, B and T have unique common fixed point in X . Again, taking $A = I$, the identity map on X , in theorem 3.1 we have another result for three self maps none of which is continuous and just a pair of them is needed to be weak compatible only.

Corollary 3.4. Let B, S and T be self mappings of complete probabilistic 2-metric space (X, F, \min) satisfying :

$$B(X) \subset S(X), T \text{ is onto}; \quad \dots(3.11)$$

$$(B, T) \text{ is weak compatible}; \quad \dots(3.12)$$

$$\forall x, y \in X \text{ and } t > 0, \quad \dots(3.13)$$

$$F_{x, By, a}(t) \geq rF_{Sx, Ty, a}(t),$$

where $r : [0, 1] \rightarrow [0, 1]$ is continuous function such that $r(t) > t$ for each $0 < t < 1$.

Then B, S and T have a unique common fixed point in X .

Again on taking $S = T = I$ the identity map in theorem 3.1, the conditions (3.1), (3.2) and (3.3) are satisfied trivially and we get the following important result.

Corollary 3.5. Let A and B be self mappings of complete

probabilistic 2-metric space (X, F, \min) satisfying :

$$F_{Ax, By, a}(t) \geq rF_{x, y, a}(t)$$

$\forall x, y \in X$, where $r : [0, 1] \rightarrow [0, 1]$ is continuous function such that $r(t) > t$ for each $0 < t < 1$.

Then A and B have a unique common fixed point in X .

Now, taking $A = I$ and $B = I$ in theorem 3.1, the conditions (3.2), (3.3) are satisfied trivially and we get an important result for surjective maps as follows.

Corollary 3.6. Let S and T be self mappings of complete probabilistic 2-metric space (X, F, \min) satisfying :

$$F_{x, y}(t) \geq rF_{Sx, Ty}(t)$$

$\forall x, y \in X$, where $r : [0, 1] \rightarrow [0, 1]$ is continuous function such that $r(t) > t$ for each $0 < t < 1$.

Then S and T have a unique common fixed point in X .

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