



A Fixed Point Theorem on Reciprocally Continuous Self Maps

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ABSTRACT

The aim of this paper is to prove a unique common fixed point theorem which generalizes the result of Aage C.T. and Salunke J.N. by weaker conditions. The conditions continuity and completeness of a metric space are replaced by weaker conditions such as compatible pair of reciprocally continuous self maps.

Keywords: Reciprocally continuous, compatible maps, fixed point, self maps

INTRODUCTION

According to G. Jungck [4] two self maps S and T of a Metric Space (X, d) are said to be compatible mappings if $\lim_{n \rightarrow \infty} d(STx_n, TSx_n) = 0$ whenever $\langle x_n \rangle$ is a sequence in X such that $\lim_{n \rightarrow \infty} Sx_n = \lim_{n \rightarrow \infty} Tx_n = t$ for some t belongs to X .

Two self maps S and T of a Metric Space (X, d) are said to be Reciprocally continuous if $\lim_{n \rightarrow \infty} STx_n = St$ and $\lim_{n \rightarrow \infty} TSx_n = Tt$ whenever $\langle x_n \rangle$ is a sequence in X such that $\lim_{n \rightarrow \infty} Sx_n = \lim_{n \rightarrow \infty} Tx_n = t$ for some t belongs to X .

Definition 1.1: A function $\phi : [0, \infty) \rightarrow [0, \infty)$ is said to be a contractive modulus if $\phi(0) = 0$ and $\phi(t) < t$ for $t > 0$.

Definition 1.2: A real valued function ϕ defined on $X \subseteq \mathbb{R}$ is said to be upper semicontinuous if $\lim_{n \rightarrow \infty} \phi(t_n) \leq \phi(t)$, for every sequence $\{t_n\} \in X$ with $t_n \rightarrow t$ as $n \rightarrow \infty$.

Aage C.T. and Salunke J.N. [1] proved the following theorem:-

Theorem A: Suppose S, I, T and J are four self mappings of a complete metric space (X, d) into itself satisfying the conditions

- (i) $S(X) \subset J(X), T(X) \subset I(X)$.
- (ii) $d^2(Sx, Ty) \leq \max \{ \phi(d(Ix, Jy))\phi(d(Ix, Sx)), \phi(d(Ix, Jy))\phi(d(Jy, Ty)), \phi(d(Ix, Sx))\phi(d(Jy, Ty)), \phi(d(Ix, Ty))\phi(d(Jy, Sx)) \}$,

for all $x, y \in X$.

- (iii) ϕ is contractive modulus as in definition (1.2).

- (iv) one of S, I, T and J is continuous.

And if

- (v) the pairs (S, I) and (T, J) are compatible of type (A).

Then S, I, T and J have a unique common fixed point.

Now we prove the following theorem.

Theorem B. Suppose S, I, T and J are four self mappings of a metric space (X, d) into itself satisfying the conditions

- (i) $S(X) \subset J(X), T(X) \subset I(X)$.
(ii) $d^2(Sx, Ty) \leq \max \{ \varphi(d(Ix, Jy))\varphi(d(Ix, Sx)), \varphi(d(Ix, Jy))\varphi(d(Jy, Ty)), \varphi(d(Ix, Sx))\varphi(d(Jy, Ty)), \varphi(d(Ix, Ty))\varphi(d(Jy, Sx)) \}$,
for all $x, y \in X$.

- (iii) φ is contractive modulus as in definition (1.2).
(iv) the pairs (S, I) and (T, J) are compatible pairs of reciprocally continuous mappings.
Then S, I, T and J have a unique common fixed point.

Proof: Let x_0 in X be arbitrary. Choose a point x_1 in X such that $Sx_0 = Jx_1$. This can be done since $S(X) \subset J(X)$. Let x_2 be a point in X such that $Tx_1 = Ix_2$. This can be done since $T(X) \subset I(X)$. In general we can choose $x_{2n}, x_{2n+1}, x_{2n+2}, \dots$ such that $Sx_{2n} = Jx_{2n+1}$ and $Tx_{2n+1} = Ix_{2n+2}$, so that we obtain a sequence

$$Sx_0, Tx_1, Sx_2, Tx_3, \dots \quad (1)$$

Taking condition (i), (ii) and (iii) as in Aage and Salunke [1] $\{Sx_{2n}\}$ is a Cauchy sequence and consequently the sequence (1) is a Cauchy. The sequence (1) converges to a limit z in X . Hence the subsequences $\{Sx_{2n}\} = \{Jx_{2n+1}\}$ and $\{Tx_{2n-1}\} = \{Ix_{2n}\}$ also converge to the limit point z .

Suppose that the pair (S, I) is compatible pair of reciprocally continuous. By the definition of reciprocally continuous, there is a sequence $\langle x_n \rangle$ in X such that

$$Sx_{2n} \rightarrow z, Ix_{2n} \rightarrow z \text{ then } SIx_{2n} \rightarrow Sz, ISx_{2n} \rightarrow Iz \text{ as } n \rightarrow \infty. \quad \dots(2)$$

Since the pair (S, I) is compatible we have $Sx_{2n} \rightarrow z, Ix_{2n} \rightarrow z$ as $n \rightarrow \infty$ and

$$\lim_{n \rightarrow \infty} d(SIx_{2n}, ISx_{2n}) = 0. \quad \dots(3)$$

using (2) and (3) we get

$$d(Sz, Iz) = 0 \text{ or } Sz = Iz.$$

Since $Sz = Iz$, .

Now by (ii)

$$d^2(Sz, Tx_{2n+1}) \leq \max \{ \varphi(d(Iz, Jx_{2n+1}))\varphi(d(Iz, Sz)), \varphi(d(Iz, Jx_{2n+1}))\varphi(d(Jx_{2n+1}, Tx_{2n+1})), \varphi(d(Iz, Sz))\varphi(d(Jx_{2n+1}, Tx_{2n+1})), \varphi(d(Iz, Tx_{2n+1}))\varphi(d(Jx_{2n+1}, Sz)) \}.$$

$Jx_{2n+1} \rightarrow z, Tx_{2n+1} \rightarrow z$ as $n \rightarrow \infty$ and $Iz = Sz$, so letting $n \rightarrow \infty$ we get

$$d^2(Sz, z) \leq \max \{ \varphi(d(Sz, z))\varphi(d(Sz, Sz)), \varphi(d(Sz, z))\varphi(d(z, z)), \varphi(d(Sz, Sz))\varphi(d(z, z)), \varphi(d(Sz, z))\varphi(d(z, Sz)) \}, \\ = \varphi(d(Sz, z))\varphi(d(z, Sz))$$

i.e. $d(Sz, z) \leq \varphi(d(Sz, z)) \leq d(Sz, z)$. Hence $\varphi(d(Sz, z)) = 0$ i.e. $Sz = z$ Thus $Sz = Iz = z$

Further

Since $S(X) \subset J(X)$, there is a point $w \in X$ such that $z = Sz = Jw$.

Now we prove that $Jw = Tw$. Now by (ii)

$$d^2(Sz, w) \leq \max \{ \varphi(d(Iz, Jw))\varphi(d(Iz, Sz)), \varphi(d(Iz, Jw))\varphi(d(Jw, Tw)), \varphi(d(Iz, Sz))\varphi(d(Jw, Tw)), \varphi(d(Iz, Tw))\varphi(d(Jw, Sz)) \} \\ = \max \{ \varphi(d(Jw, Jw))\varphi(d(Jw, Jw)), \varphi(d(Jw, Jw))\varphi(d(Jw, Tw)), \varphi(d(Jw, Jw))\varphi(d(Jw, Tw)), \varphi(d(Jw, Tw))\varphi(d(Jw, Jw)) \}$$

so $d^2(Jw, Tw) \leq 0$ implies $d(Jw, Tw) = 0$, hence $z = Jw = Tw$.

Since the pair (T, J) is compatible pair of reciprocally continuous. By the definition of reciprocally continuous, there is a sequence $\langle x_n \rangle$ in X such that

$$Tx_{2n} \rightarrow z, Jx_{2n} \rightarrow z \text{ then } TJx_{2n} \rightarrow Tz, JTx_{2n} \rightarrow Jz \text{ as } n \rightarrow \infty. \quad \dots(4)$$

Since the pair (T, J) is compatible we have $Tx_{2n} \rightarrow z, Jx_{2n} \rightarrow z$ as $n \rightarrow \infty$ and

$$\lim_{n \rightarrow \infty} d(TJx_{2n}, JTx_{2n}) = 0. \quad \dots(5)$$

using (4) and (5) we get

$$\begin{aligned} d(Tz, Jz) &= 0, \text{ hence } Tz = Jz. \text{ Now} \\ d^2(z, Tz) &= d^2(Sz, Tz) \\ &\leq \max \{ \varphi(d(Iz, Jz))\varphi(d(Iz, Sz)), \varphi(d(Iz, Jz))\varphi(d(Jz, Tz)), \\ &\quad \varphi(d(Iz, Sz))\varphi(d(Jz, Tz)), \varphi(d(Iz, Tz))\varphi(d(Jz, Sz)) \} \\ &= \max \{ \varphi(d(z, Tz))\varphi(d(z, z)), \varphi(d(z, Tz))\varphi(d(Tz, Tz)), \\ &\quad \varphi(d(z, z))\varphi(d(Tz, Tz)), \varphi(d(z, Tz))\varphi(d(Tz, z)) \} \\ &= \varphi(d(Tz, z))\varphi(d(Tz, z)) \end{aligned}$$

implies that $d(Tz, z) \leq \varphi(d(Tz, z)) \leq d(Tz, z)$.

Hence $\varphi(d(Tz, z)) = 0$ i.e. $Tz = z$ and $z = Tz = Jz$. So z is a common fixed point of S, I, J and T .

Uniqueness:

Let z' be another common fixed point of S, I, J and T . i.e. $z' = Sz' = Iz' = Tz' = Jz'$. From condition (ii) we have

$$\begin{aligned} d^2(z, z') &= d^2(Sz, Tz') \\ &\leq \max \{ \varphi(d(Iz, Jz'))\varphi(d(Iz, Sz)), \varphi(d(Iz, Jz'))\varphi(d(Jz', Tz')), \\ &\quad \varphi(d(Iz, Sz))\varphi(d(Jz', Tz')), \varphi(d(Iz, Tz'))\varphi(d(Jz', Sz)) \} \\ &= \max \{ \varphi(d(z, z'))\varphi(d(z, z)), \varphi(d(z, z'))\varphi(d(z', z')), \\ &\quad \varphi(d(z, z))\varphi(d(z', z')), \varphi(d(z, z'))\varphi(d(z', z)) \} \end{aligned}$$

Therefore $d(z, z') \leq \varphi(d(z, z')) \leq d(z, z')$ i.e. $\varphi(d(z, z')) = d(z, z')$. Thus $d(z, z') = 0$ i.e. $z' = z$. Hence the common fixed point is unique.

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